
Benefits from U.S. Monetary Policy Experimentation in the Days of Samuelson and Solow and Lucas

Timothy Cogley, Riccardo Colacito and Thomas Sargent

The economy

- ▶ Central Bank chooses v_t to

$$\min E_0 \sum_{t=0}^{\infty} \beta^t (U_t^2 + \lambda v_t^2), s.t.$$

- ▶ Model 1:

$$\begin{aligned} U_t &= \bar{U}_1 + A_1 U_{t-1} + B_1 \pi_t + C_{U,1} \eta_{1,t} \\ \pi_t &= v_{t-1} + C_{\pi} \eta_{3,t} \end{aligned}$$

- ▶ Model 2:

$$\begin{aligned} U_t &= \bar{U}_2 + A_2 U_{t-1} + B_2 (\pi_t - v_{t-1}) + C_{U,2} \eta_{2,t} \\ \pi_t &= v_{t-1} + C_{\pi} \eta_{3,t} \end{aligned}$$

The economy

- ▶ Central Bank chooses v_t to

$$\min E_0 \sum_{t=0}^{\infty} \beta^t (U_t^2 + \lambda v_t^2), s.t.$$

- ▶ Model 1 (α_t):

$$\begin{aligned} U_t &= \bar{U}_1 + A_1 U_{t-1} + B_1 \pi_t + C_{U,1} \eta_{1,t} \\ \pi_t &= v_{t-1} + C_{\pi} \eta_{3,t} \end{aligned}$$

- ▶ Model 2 ($1 - \alpha_t$):

$$\begin{aligned} U_t &= \bar{U}_2 + A_2 U_{t-1} + B_2 (\pi_t - v_{t-1}) + C_{U,2} \eta_{2,t} \\ \pi_t &= v_{t-1} + C_{\pi} \eta_{3,t} \end{aligned}$$

- ▶ Bayesian updating:

$$\alpha_t = B(\alpha_{t-1}, U_t)$$

The economy

- ▶ Central Bank chooses v_t to

$$\min E_0 \sum_{t=0}^{\infty} .995^t (U_t^2 + 0.1v_t^2), s.t.$$

- ▶ Model 1 (α_t):

$$U_t = 0.0023 + 0.7971U_{t-1} - 0.2761\pi_t + 0.0054\eta_{1,t}$$

$$\pi_t = v_{t-1} + 0.0055\eta_{3,t}$$

- ▶ Model 2 ($1 - \alpha_t$):

$$U_t = 0.0007 + 0.8468U_{t-1} - 0.2489(\pi_t - v_{t-1}) + 0.0055\eta_{2,t}$$

$$\pi_t = v_{t-1} + 0.0055\eta_{3,t}$$

- ▶ Bayesian updating:

$$\alpha_t = B(\alpha_{t-1}, U_t)$$

Plan of the talk

- ▶ Use Bayes' law to get a transition equation for α_t
- ▶ Bellman equations
 1. Bayesian problem
 2. Anticipated utility
- ▶ Policy and value functions
- ▶ Experiments

Evolution of α_t

- ▶ Using Bayes' law:

$$\log \frac{\alpha_t}{1 - \alpha_t} = \log \frac{\alpha_{t-1}}{1 - \alpha_{t-1}} + \log \frac{p_1(U_t | U_{t-1}, v_{t-1})}{p_2(U_t | U_{t-1}, v_{t-1})}$$

- ▶ Timing protocol



Evolution of α_t

- Using Bayes' law:

$$\log \frac{\alpha_t}{1 - \alpha_t} = \log \frac{\alpha_{t-1}}{1 - \alpha_{t-1}} + \log \frac{p_1(U_t | U_{t-1}, v_{t-1})}{p_2(U_t | U_{t-1}, v_{t-1})}$$

- Timing protocol



- α_t is a martingale from the point of view of the Bayesian agent.
- If the prior attaches nonzero probability to the model that actually generates the economy, then α_t converges almost surely under that measure.

Bayesian Problem

$$\begin{aligned} V(U_t, \alpha_t) = \max_{v_t} & \left\{ -(U_t^2 + \lambda v_t^2) \right. \\ & + \beta \alpha_t \int V(U_{1,t+1}, B(\alpha_t, U_{1,t+1})) dF(\varepsilon_{1,t+1}) \\ & \left. + \beta(1 - \alpha_t) \int V(U_{2,t+1}, B(\alpha_t, U_{2,t+1})) dF(\varepsilon_{2,t+1}) \right\} \end{aligned}$$

subject to:

$$U_{1,t+1} = \bar{U}_1 + A_1 U_t + B_1 v_t + C_1 \varepsilon_{1,t+1}$$

$$U_{2,t+1} = \bar{U}_2 + A_2 U_t + C_2 \varepsilon_{2,t+1}$$

Anticipated Utility

► Bellman equation:

$$\begin{aligned} W(U_t, \alpha) = \max_{v_t} & \left\{ -(U_t^2 + \lambda v_t^2) \right. \\ & + \beta \alpha \int W(U_{1,t+1}, \alpha) dF(\varepsilon_{1,t+1}) \\ & \left. + \beta(1 - \alpha) \int W(U_{2,t+1}, \alpha) dF(\varepsilon_{2,t+1}) \right\} \end{aligned}$$

subject to:

$$U_{1,t+1} = \bar{U}_1 + A_1 U_t + B_1 v_t + C_1 \varepsilon_{1,t+1}$$

$$U_{2,t+1} = \bar{U}_2 + A_2 U_t + C_2 \varepsilon_{2,t+1}$$

Anticipated Utility

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► Policy function

$$v_t = w(U_t, \alpha)$$

Anticipated Utility

► Bellman equation:

$$\begin{aligned} W(U_t, \alpha) = \max_{v_t} & \left\{ -(U_t^2 + \lambda v_t^2) \right. \\ & + \beta \alpha \int W(U_{1,t+1}, \alpha) dF(\varepsilon_{1,t+1}) \\ & \left. + \beta(1 - \alpha) \int W(U_{2,t+1}, \alpha) dF(\varepsilon_{2,t+1}) \right\} \end{aligned}$$

► Policy function

$$\begin{aligned} v_t &= w(U_t, \alpha_t) \\ \alpha_t &= B(\alpha_{t-1}, U_t) \end{aligned}$$

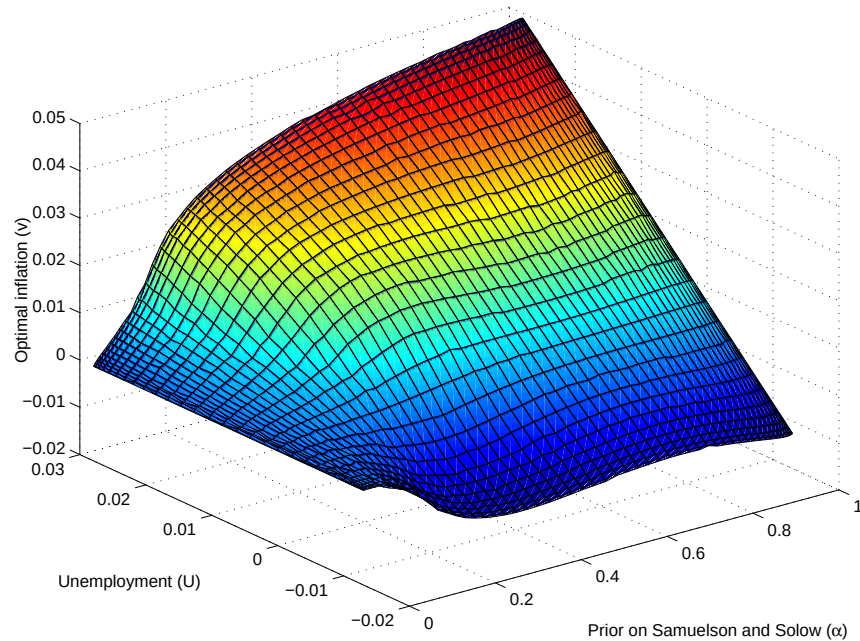
Value function for anticipated utility

$$\begin{aligned} W(s_t; \alpha_t) &= r(s_t, w(s_t, \alpha_t)) \\ &+ \beta \alpha_t \int W(U_{1,t+1}, B(\alpha_t, U_{1,t+1})) dF(\epsilon_{1,t+1}) \\ &+ \beta (1 - \alpha_t) \int W(U_{2,t+1}, B(\alpha_t, U_{2,t+1})) dF(\epsilon_{2,t+1}). \end{aligned}$$

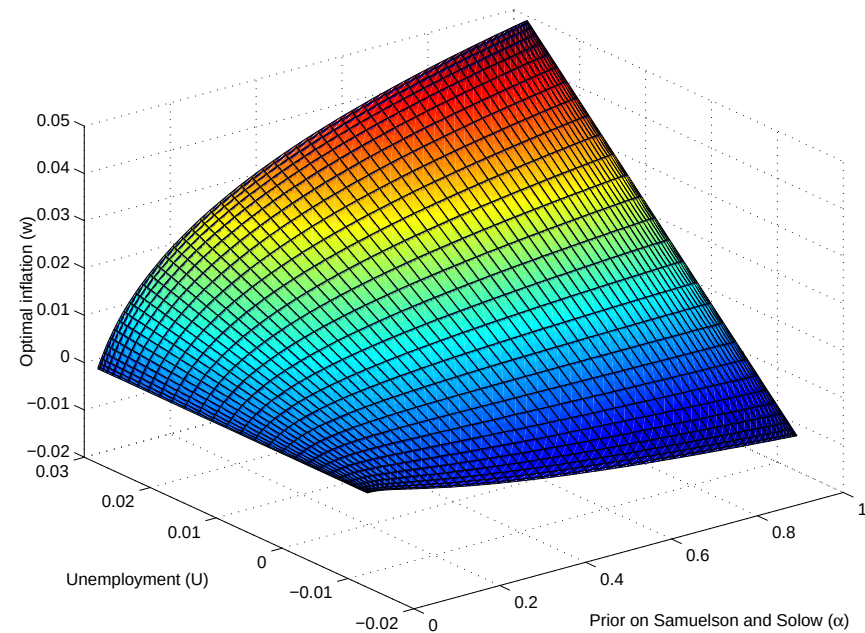
$$U_{1,t+1} = A_1 s_t + B_1 w(s_t, \alpha_t) + C_1 \epsilon_{1,t+1}$$

$$U_{2,t+1} = A_1 s_t + B_1 w(s_t, \alpha_t) + C_1 \epsilon_{1,t+1}$$

Policy functions

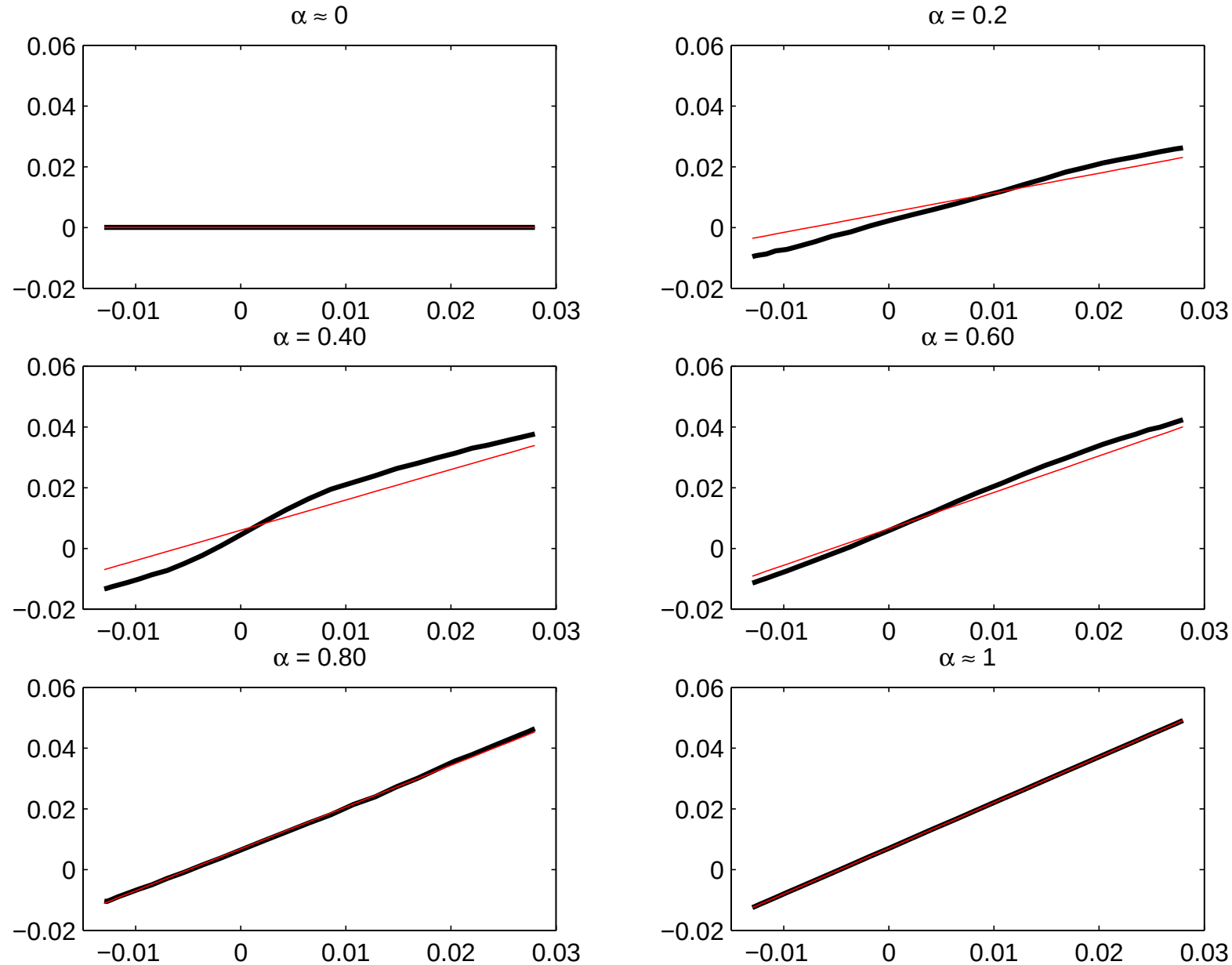


(a) Bayesian Problem

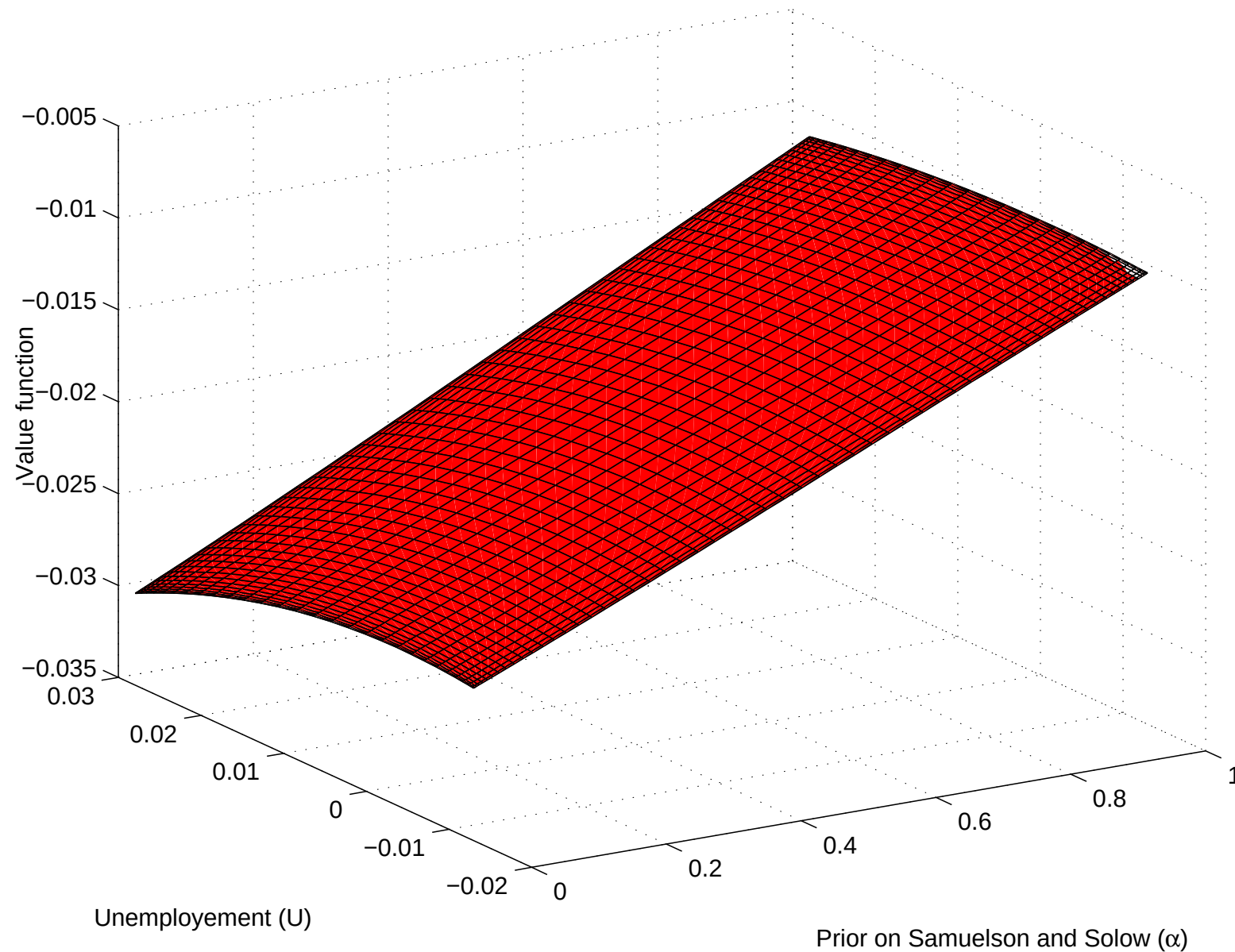


(b) Anticipated Utility

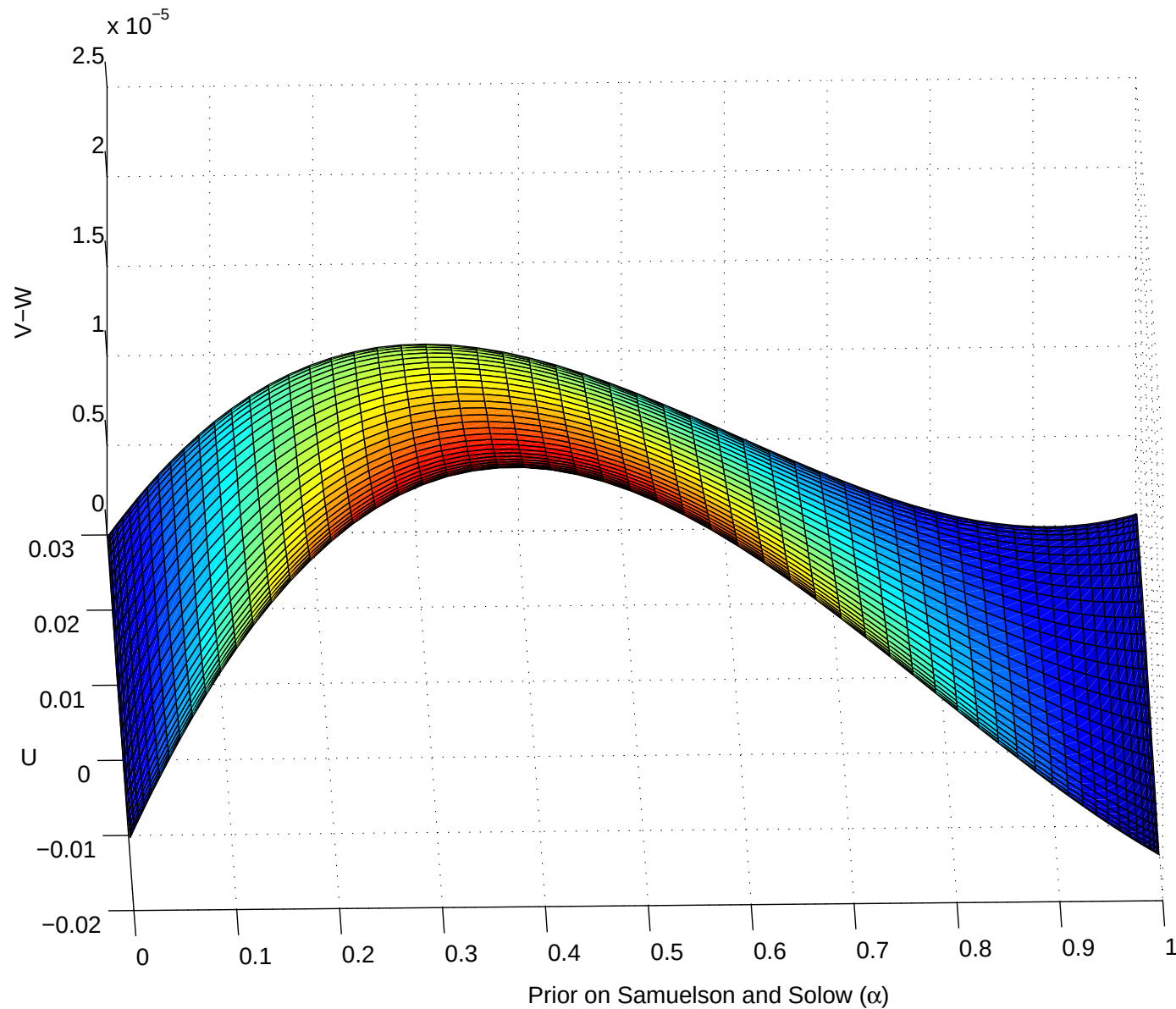
Policy functions (Slices)



Value functions



Value of experimentation

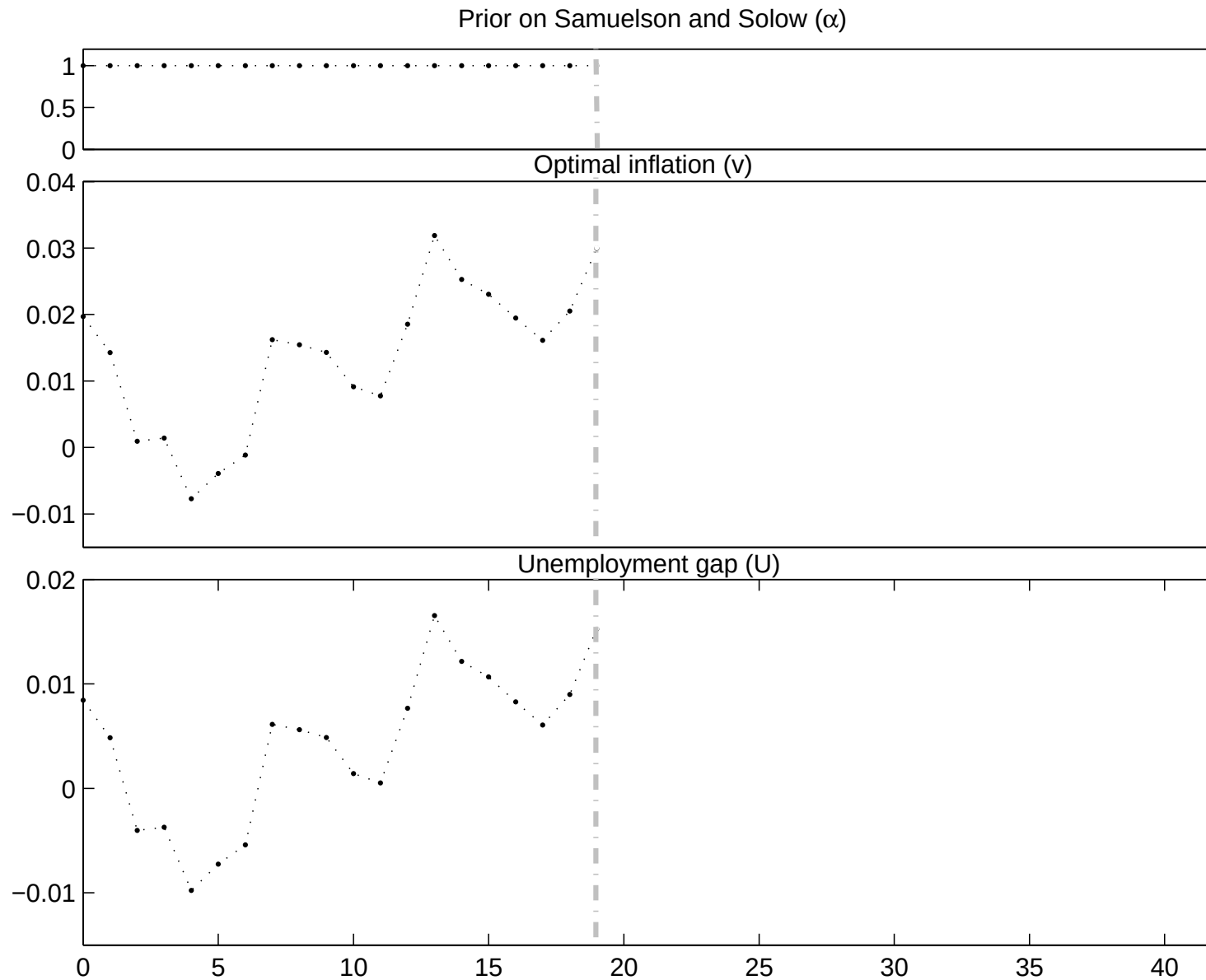


Learning Experiments

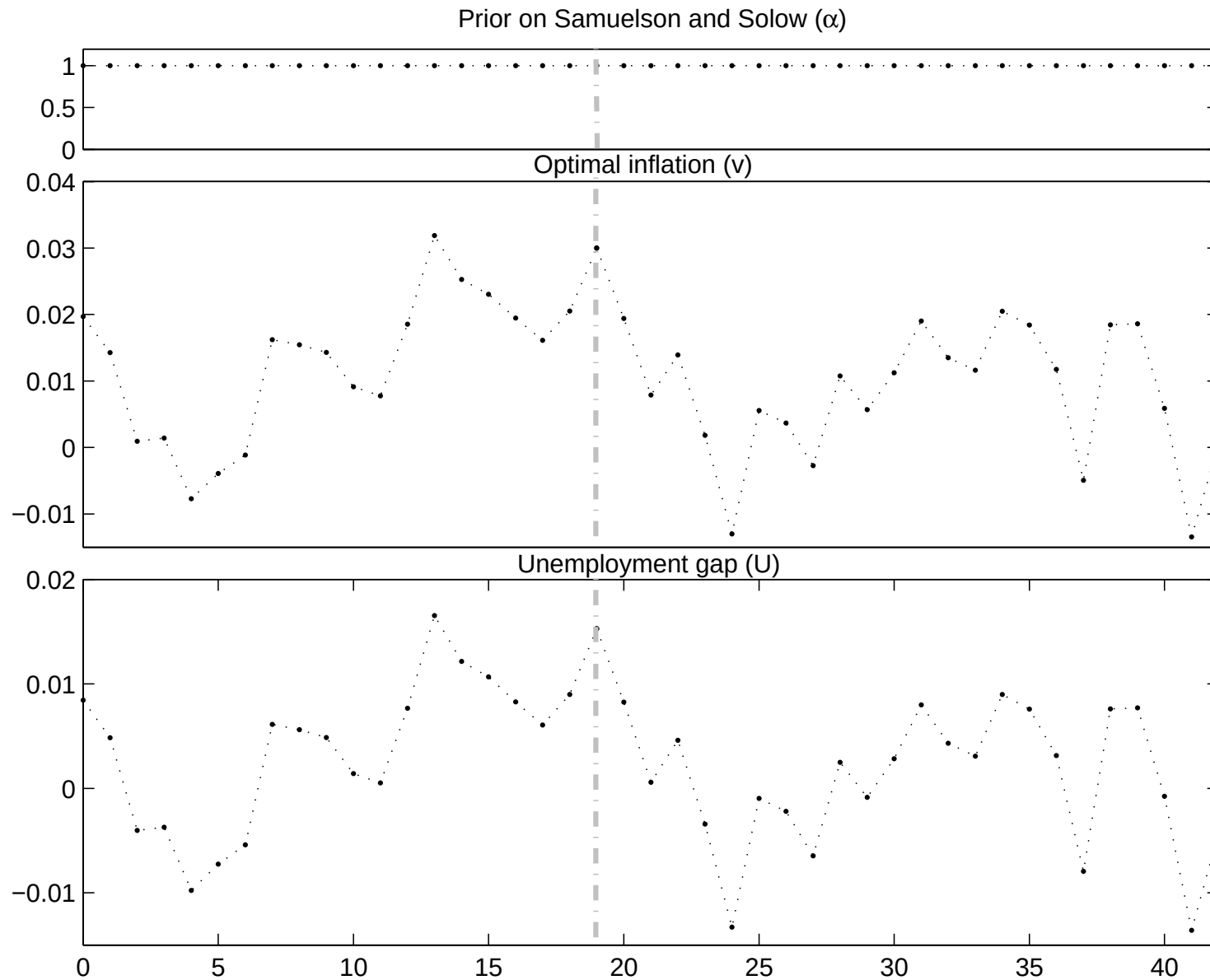
Suppose that one model generates the data:

- ▶ How long does it take to learn it?
- ▶ How much faster can we learn it with experimentation?
- ▶ How different are inflation and unemployment in the learning process?

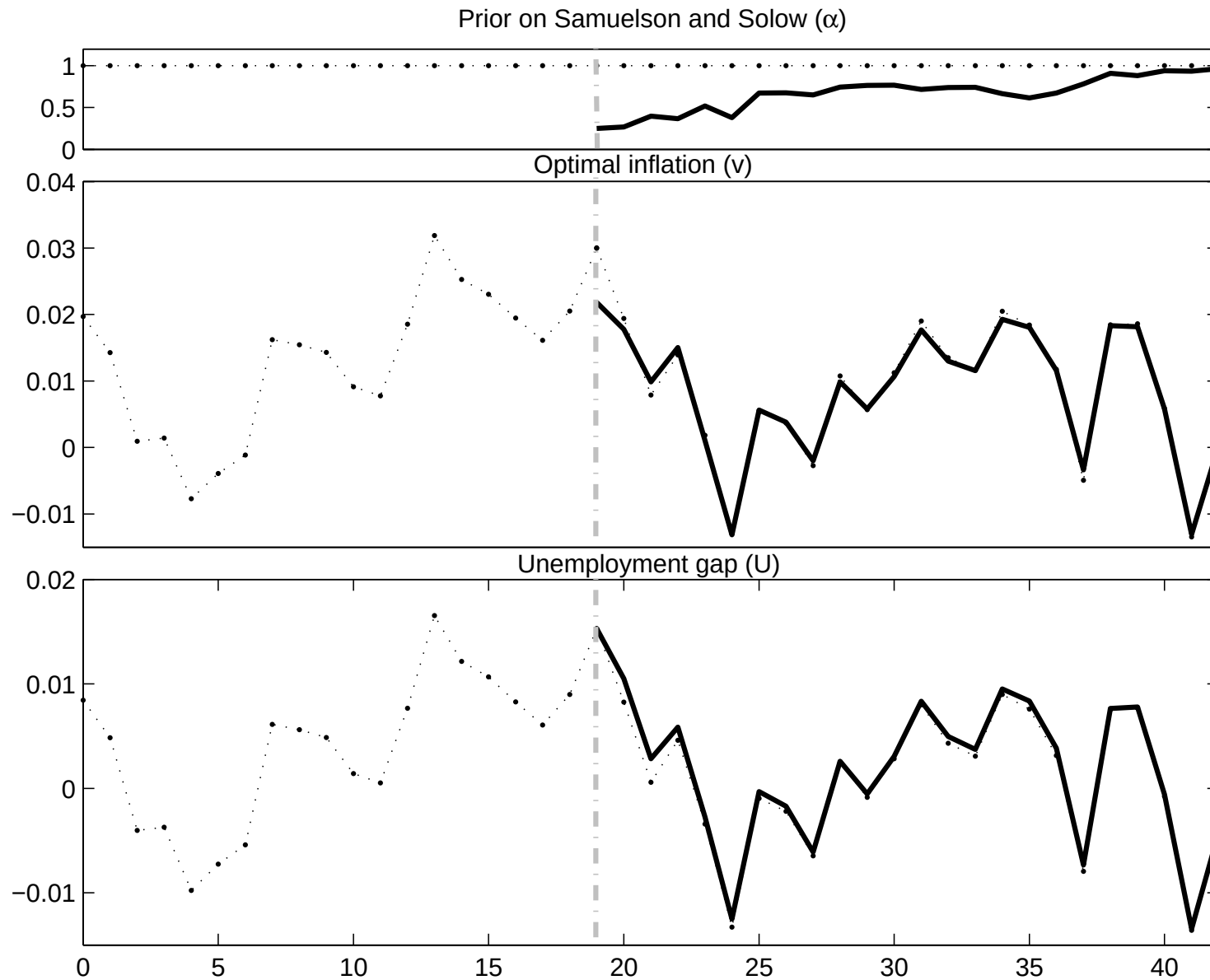
Forgetting Lucas



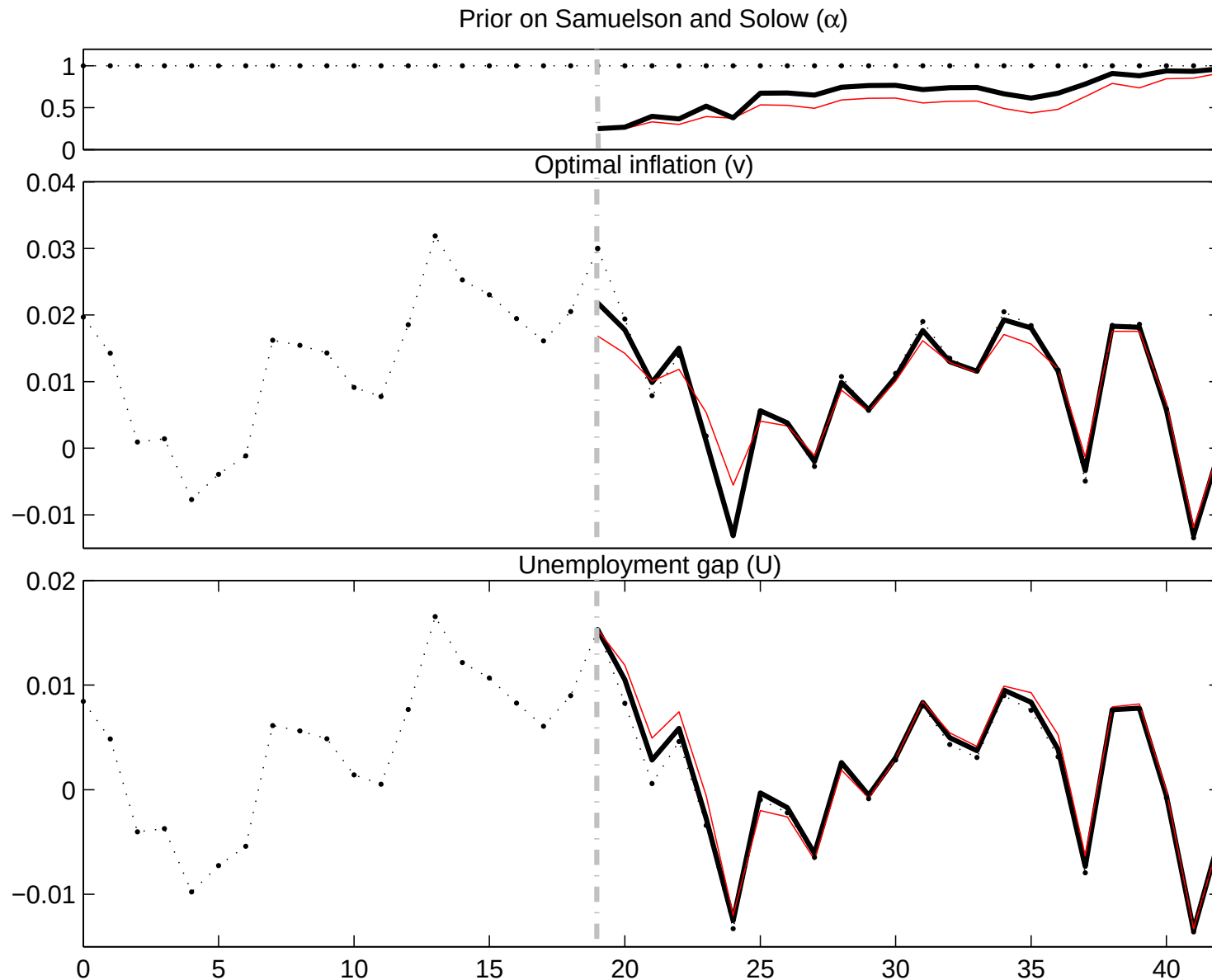
Forgetting Lucas



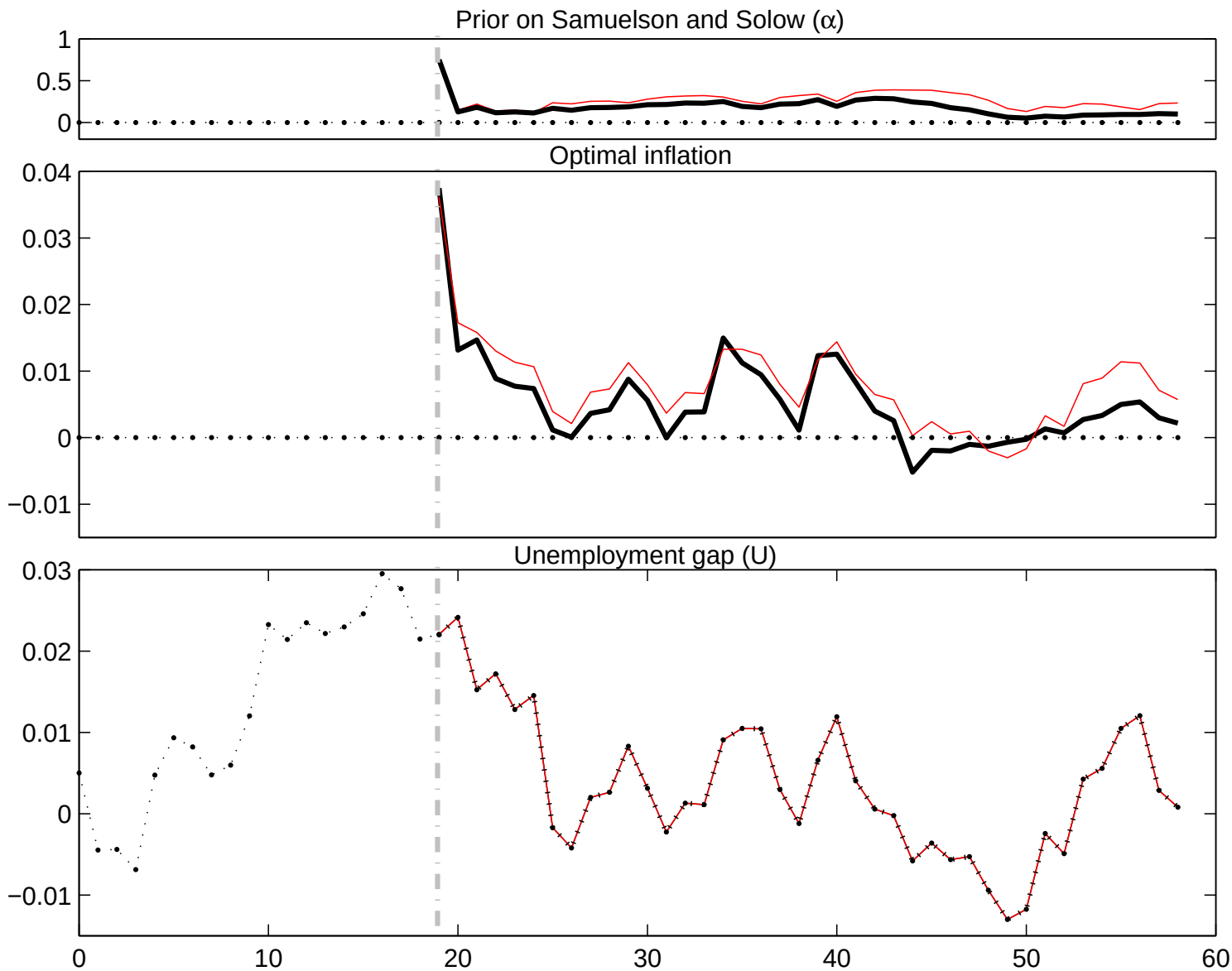
Forgetting Lucas



Forgetting Lucas



Forgetting Samuelson and Solow



Conclusions

- ▶ Benefits of experimentation, but not too big.
- ▶ Samuelson-Solow is less sensitive to small doubts.
- ▶ Limitations:
 1. Only two models are on the table.
 2. Models' parameters are assumed to be known.
- ▶ How do results vary with λ ?