

1 The non-linear equilibrium system

$$e_t \left[\frac{C_t^w}{(C_{t-1}^w)^\varphi} \right]^{1-\gamma_w} - \beta_w \varphi E_t \left\{ e_{t+1} \left[\frac{C_{t+1}^w}{(C_t^w)^\varphi} \right]^{1-\gamma_w} \right\} = C_t^w \lambda_t^w \quad (1.1)$$

$$\frac{\eta}{(1-H_t)^\xi} = \lambda_t^w W_t \quad (1.2)$$

$$\frac{\lambda_t^w}{R_t^D} = \beta_w E_t \left(\frac{\lambda_{t+1}^w}{\pi_{t+1}} \right) \quad (1.3)$$

$$e_t \left[\frac{C_t^b}{(C_{t-1}^b)^\varphi} \right]^{1-\gamma_b} - \beta_b \varphi E_t \left\{ e_{t+1} \left[\frac{C_{t+1}^b}{(C_t^b)^\varphi} \right]^{1-\gamma_b} \right\} = C_t^b \lambda_t^b \quad (1.4)$$

$$\frac{\lambda_t^b}{R_t} = \beta_b E_t \left[\frac{\lambda_{t+1}^b}{\pi_{t+1}} \right] \quad (1.5)$$

$$E_t R_{t+1}^Z = E_t \left\{ \frac{1}{1-\delta_t^Z} \left[\frac{R_t Q_t^Z}{Q_{t+1}^Z} \left(1 + \chi^z \left(\frac{Z_t}{Z_{t-1}} - 1 \right) \frac{Z_t}{Z_{t-1}} \right) - \chi^z \left(\frac{Z_{t+1}}{Z_t} - 1 \right) \left(\frac{Z_{t+1}}{Z_t} \right)^2 \pi_{t+1} \right] \right\} \quad (1.6)$$

$$\begin{aligned} \frac{1+\vartheta_D}{\vartheta_D} (R_t^D - 1) &= R_t - 1 - \frac{\phi_R}{\vartheta_D} \left(\frac{R_t^D}{R_{t-1}^D} - 1 \right) \frac{R_t^D}{R_{t-1}^D} \\ &+ \frac{\beta_b \phi_R}{\vartheta_D} \left(\frac{R_{t+1}^D}{R_t^D} - 1 \right) \frac{R_{t+1}^D}{R_t^D} \end{aligned} \quad (1.7)$$

$$B_t^L = (1-s_t)D_t + Q_t^Z Z_t \quad (1.8)$$

$$B_t^L + L_t = Q_t^Z Z_t + D_t + m_t + (\Gamma_t - 1)(s_t D_t + m_t) \quad (1.9)$$

$$rp_t^B = \left(\frac{D_t}{(1-\mu_t)L_t + B_t^L} \right)^v \quad (1.10)$$

$$rp_t^\kappa = \left(\frac{\bar{\kappa} - \kappa_t}{\bar{\kappa}} Q_t^Z Z_t \right)^{-\xi} \quad (1.11)$$

$$R_t^L = R_t + R_t \nu \left(\frac{D_t}{(1-\mu_t)L_t + B_t^L} \right)^{1+v} \quad (1.12)$$

$$R_t^L - R_t rp_t^B = \xi \left(\frac{\bar{\kappa} - \kappa_t}{\bar{\kappa}} Q_t^Z Z_t \right)^{-\xi} \frac{E_t R_{t+1}^Z}{\bar{\kappa} - \kappa_t} \quad (1.13)$$

$$\delta_t^Z = E_t \left[\frac{\pi_{t+1}}{\chi_{\delta^z} Q_t^Z Z_t} \right] \quad (1.14)$$

$$L_t = (s_t D_t + m_t) \Gamma_t \quad (1.15)$$

$$L_t = \kappa_t Q_t^Z Z_t \Gamma_t \quad (1.16)$$

$$R_t^L = \Gamma_t^{-1} [R_t rp_t^B + \kappa_t^{-1} (R_{t+1}^Z rp_t^\kappa - R_t) Q_t^Z] \quad (1.17)$$

$$E_t F_{t+1} = E_t \left[\frac{r_{t+1}^K + (1-\delta)Q_{t+1}^K}{Q_t^K} \right] \quad (1.18)$$

$$E_t F_{t+1} = E_t \left[\frac{R_t^L}{\pi_{t+1}} r p_t^E \right] \quad (1.19)$$

$$L_t = Q_t^K K_{t+1} - N_t \quad (1.20)$$

$$r p_t^E = \left(\frac{Q_t^K K_{t+1}}{N_t} \right)^{\psi_t} \quad (1.21)$$

$$N_t = \nu [F_t Q_{t-1}^K K_t - E_{t-1} F_t (Q_{t-1}^K K_t - N_{t-1})] + (1 - \nu) g_t \quad (1.22)$$

$$Y_t = A_t K_t^\alpha H_t^{1-\alpha} \quad (1.23)$$

$$\frac{1}{Q_t^K} = x_t - \chi_I \left(\frac{I_t}{I_{t-1}} - 1 \right) \frac{I_t}{I_{t-1}} + \beta_w \chi_I E_t \left[\left(\frac{I_{t+1}}{I_t} - 1 \right) \left(\frac{I_{t+1}}{I_t} \right)^2 \frac{Q_{t+1}^K \lambda_{t+1}^w}{Q_t^K \lambda_t^w} \right] \quad (1.24)$$

$$K_{t+1} = (1 - \delta) K_t + x_t I_t - \frac{\chi_I}{2} \left(\frac{I_t}{I_{t-1}} - 1 \right)^2 I_t \quad (1.25)$$

$$\log(R_t/R) = \varrho_\pi \log(\pi_t/\pi) + \varrho_Y \log(Y_t/Y) + \varepsilon_{R_t} \quad (1.26)$$

$$Y_t = C_t^w + C_t^b + I_t + G_t \quad (1.27)$$

$$C_t = C_t^w + C_t^b \quad (1.28)$$

$$\ln(A_t) = (1 - \rho_A) \ln(A) + \rho_A \ln(A_{t-1}) + \varepsilon_{A_t} \quad (1.29)$$

$$\ln(x_t) = (1 - \rho_x) \ln(x) + \rho_x \ln(x_{t-1}) + \varepsilon_{x_t} \quad (1.30)$$

$$\ln(e_t) = (1 - \rho_e) \ln(e) + \rho_e \ln(e_{t-1}) + \varepsilon_{e_t} \quad (1.31)$$

$$\ln(G_t) = (1 - \rho_G) \ln(G) + \rho_G \ln(G_{t-1}) + \varepsilon_{G_t} \quad (1.32)$$

$$\ln(\psi_t) = (1 - \rho_\psi) \ln(\psi) + \rho_\psi \ln(\psi_{t-1}) + \varepsilon_{\psi_t} \quad (1.33)$$

$$\ln(\Gamma_t) = (1 - \rho_\Gamma) \ln(\Gamma) + \rho_\Gamma \ln(\Gamma_{t-1}) + \varepsilon_{\Gamma_t} \quad (1.34)$$

$$\ln(\mu_t) = (1 - \rho_\mu) \ln(\mu) + \rho_\mu \ln(\mu_{t-1}) + \varepsilon_{\mu_t} \quad (1.35)$$

$$\ln(m_t) = (1 - \rho_m) \ln(m) + \rho_m \ln(m_{t-1}) + \varepsilon_{m_t} \quad (1.36)$$

$$r_t^K = \alpha m c_t \frac{Y_t}{K_t} \quad (1.37)$$

$$W_t = (1 - \alpha) m c_t \frac{Y_t}{H_t} \quad (1.38)$$

$$\tilde{P}_t(j) = \frac{\theta}{\theta - 1} \frac{E_t \sum_{l=0}^{\infty} (\beta_w \phi_p)^l \lambda_{t+l}^w Y_{t+l}(j) m c_{t+l}}{E_t \sum_{l=0}^{\infty} (\beta_w \phi_p)^l \lambda_{t+l}^w Y_{t+l}(j) \pi^l / P_{t+l}} \quad (1.39)$$

2 Steady-States

Letters without subscript represent the steady-state of the variable. So, for instance, Y is the steady-state of output.

$$\frac{1}{Q^K} = x = 1 \quad (2.1)$$

$$mc = \frac{\theta - 1}{\theta} \quad (2.2)$$

$$R^Z = \frac{R}{(1 - \delta^Z)} \quad (2.3)$$

$$r^K = \alpha mc \frac{1}{\frac{K}{Y}} \quad (2.4)$$

$$F = r^K + 1 - \delta \quad (2.5)$$

$$R^L = \left(\frac{F\pi}{rp^E} \right) \quad (2.6)$$

$$Q^Z Z = \left[\frac{\pi}{\chi_{\delta^Z} \delta^Z} \right] \quad (2.7)$$

$$L = \kappa Q^Z Z \Gamma \quad (2.8)$$

$$D = \frac{L}{s\Gamma} \text{ since } m = 0 \quad (2.9)$$

$$B^L = (1 - s)D + Q^Z Z \quad (2.10)$$

$$N = L \quad (2.11)$$

$$K = 2N \quad (2.12)$$

$$I = \delta K \quad (2.13)$$

$$Y = K * 6.753 \quad (2.14)$$

$$G = Y * 0.17 \quad (2.15)$$

$$H = \left(\frac{Y}{A} \right)^{\frac{1}{1-\alpha}} \left(\frac{1}{K} \right)^{\frac{\alpha}{1-\alpha}} \quad (2.16)$$

$$W = (1 - \alpha) mc \frac{Y}{H} \quad (2.17)$$

$$\lambda = \frac{\eta}{(1 - H)^\zeta W} \quad (2.18)$$

$$Z = Y * 0.294 \quad (2.19)$$

$$Q^Z = \frac{Q^Z Z}{Z} \quad (2.20)$$

$$C^w = Y * 0.624 \quad (2.21)$$

$$C^b = Y * 0.037 \quad (2.22)$$

3 The log-linearized equilibrium system

\tilde{x}_t is the log-deviation of the variable x_t from its steady state x . $\tilde{x}_t = \log\left(\frac{x_t}{x}\right)$ so $\tilde{x}_t \approx \frac{x_t - x}{x}$.

$$e \left[\frac{C^w}{(C^w)^\varphi} \right]^{(1-\gamma_w)} \left\{ \tilde{e}_t + (1-\gamma_w)\tilde{C}_t^w - \varphi(1-\gamma_w)\tilde{C}_{t-1}^w \right\} - \beta_w \varphi e \left[\frac{C^w}{(C^w)^\varphi} \right]^{(1-\gamma_w)} E_t \left\{ \tilde{e}_{t+1} + (1-\gamma_w)\tilde{C}_{t+1}^w - \varphi(1-\gamma_w)\tilde{C}_t^w \right\} = C^w \lambda^w (\tilde{C}_t^w + \tilde{\lambda}_t^w) \quad (3.1)$$

$$\left[-\varsigma \frac{H}{(1-H)} \right] \tilde{H}_t = \tilde{\lambda}_t^w + \tilde{W}_t \quad (3.2)$$

$$\tilde{\lambda}_t^w - \tilde{R}_t^D = E_t \left[\tilde{\lambda}_{t+1}^w - \tilde{\pi}_{t+1} \right] \quad (3.3)$$

$$e \left[\frac{C^b}{(C^b)^\varphi} \right]^{(1-\gamma_b)} \left\{ \tilde{e}_t + (1-\gamma_b)\tilde{C}_t^b - \varphi(1-\gamma_b)\tilde{C}_{t-1}^b \right\} - \beta_b \varphi e \left[\frac{C^b}{(C^b)^\varphi} \right]^{(1-\gamma_b)} \left\{ \tilde{e}_{t+1} + (1-\gamma_b)\tilde{C}_{t+1}^b - \varphi(1-\gamma_b)\tilde{C}_t^b \right\} = C^b \lambda^b (\tilde{C}_t^b + \tilde{\lambda}_t^b) \quad (3.4)$$

$$\tilde{\lambda}_t^b - \tilde{R}_t = E_t \left[\tilde{\lambda}_{t+1}^b - \tilde{\pi}_{t+1} \right] \quad (3.5)$$

$$R^Z \tilde{R}_t^Z = -R^Z + \left[\frac{R}{(1-\delta^Z) \left(1 - \frac{\delta^Z}{1-\delta^Z} \tilde{\delta}_{t-1}^Z \right)} \right] \left(1 + \tilde{Q}_{t-1}^Z - \tilde{Q}_t^Z + \tilde{R}_{t-1} + \chi z \left(\tilde{Z}_{t-1} - \tilde{Z}_{t-2} \right) + \chi z (1-\pi) \left(\tilde{Z}_t - \tilde{Z}_{t-1} \right) \right) \quad (3.6)$$

$$\left[\left(\frac{1+\vartheta_D}{\vartheta_D} \right) R^D \right] \tilde{R}_t^D = R \tilde{R}_t + \left[(\beta_b - 1) \frac{\phi_R}{\vartheta_D} \right] (\tilde{R}_t^D - \tilde{R}_{t-1}^D) \quad (3.7)$$

$$\tilde{B}_t^L = \left[\frac{(1-s)D}{BL} \right] \tilde{D}_t - \left(\frac{Ds}{BL} \right) \tilde{s}_t + \left(\frac{Q^Z Z}{BL} \right) \left(\tilde{Z}_t + \tilde{Q}_t^Z \right) \quad (3.8)$$

$$\begin{aligned}
& B^L \tilde{B}_t^L + L \tilde{L}_t = Q^Z Z \left(\tilde{Q}_t^Z + \tilde{Z}_t \right) + D \tilde{D}_t \\
& + \Gamma s D \left(\tilde{\Gamma}_t + \tilde{s}_t + \tilde{D}_t \right) + \Gamma m \left(\tilde{\Gamma}_t + \tilde{m}_t \right) - s D \left(\tilde{s}_t + \tilde{D}_t \right)
\end{aligned} \tag{3.9}$$

$$\tilde{r}p_t^B = v \left[\tilde{D}_t + \frac{L\mu}{(1-\mu)L + B^L} \tilde{\mu}_t - \frac{(1-\mu)L}{(1-\mu)L + B^L} \tilde{L}_t - \frac{B^L}{(1-\mu)L + B^L} \tilde{B}_t^L \right] \tag{3.10}$$

$$\tilde{r}p_t^\kappa = -\xi \left[\tilde{Q}_t^Z + \tilde{Z}_t - \frac{\kappa}{\bar{\kappa} - \kappa} \tilde{\kappa}_t \right] \tag{3.11}$$

$$\begin{aligned}
& \left(\frac{R^L}{R^L - R} \right) \tilde{R}_t^L = \left(\frac{R^L}{R^L - R} \right) \tilde{R}_t \\
& + (1+v) \left[\tilde{D}_t + \frac{L\mu}{(1-\mu)L + B^L} \tilde{\mu}_t - \frac{(1-\mu)L}{(1-\mu)L + B^L} \tilde{L}_t - \frac{B^L}{(1-\mu)L + B^L} \tilde{B}_t^L \right]
\end{aligned} \tag{3.12}$$

$$\begin{aligned}
& \left(\frac{R^L}{R^L - Rrp^B} \right) \tilde{R}_t^L = \left(\frac{Rrp^B}{R^L - Rrp^B} \right) \left(\tilde{R}_t + \tilde{r}p_t^B \right) \\
& + \xi \left[\left(\frac{\kappa}{\bar{\kappa} - \kappa} \right) \tilde{\kappa}_t - \tilde{Q}_t^Z - \tilde{Z}_t \right] + \tilde{R}_{t+1}^Z + \left(\frac{\kappa}{\bar{\kappa} - \kappa} \right) \tilde{\kappa}_t
\end{aligned} \tag{3.13}$$

$$\tilde{\delta}_t^Z = E_t [\tilde{\pi}_{t+1}] - \tilde{Q}_t^Z - \tilde{Z}_t \tag{3.14}$$

$$\tilde{L}_t = \tilde{\Gamma}_t + \left(\frac{sD\Gamma}{sD\Gamma + m\Gamma} \right) \left(\tilde{s}_t + \tilde{D}_t \right) + \left(\frac{m\Gamma}{sD\Gamma + m\Gamma} \right) \tilde{m}_t \tag{3.15}$$

$$\tilde{L}_t = \tilde{\kappa}_t + \tilde{Q}_t^Z + \tilde{Z}_t + \tilde{\Gamma}_t \tag{3.16}$$

$$\begin{aligned}
& R^L \tilde{R}_t^L = \left(\frac{Rrp^B}{\Gamma} \right) \left(\tilde{R}_t + \tilde{r}p_t^B - \tilde{\Gamma}_t \right) \\
& + \left(\frac{R^Z r p^\kappa Q^Z}{\Gamma \kappa} \right) \left(\tilde{R}_{t+1}^Z + \tilde{r}p_t^\kappa + \tilde{Q}_t^Z - \tilde{\Gamma}_t - \tilde{\kappa}_t \right) - \left(\frac{RQ^Z}{\Gamma \kappa} \right) \left(\tilde{R}_t + \tilde{Q}_t^Z - \tilde{\Gamma}_t - \tilde{\kappa}_t \right)
\end{aligned} \tag{3.17}$$

$$\tilde{F}_t = -\tilde{Q}_{t-1}^K + \left(\frac{r^K}{FQ^K} \right) \tilde{r}_t^K + \left(\frac{1-\delta}{F} \right) \tilde{Q}_t^K \tag{3.18}$$

$$\tilde{F}_t = \tilde{R}_{t-1}^L - \tilde{\pi}_t + \tilde{r}p_{t-1}^E \tag{3.19}$$

$$L \tilde{L}_t = (Q^K K) \left(\tilde{Q}_t^K + \tilde{K}_t \right) - N \tilde{N}_t \tag{3.20}$$

$$\tilde{r}p_t^E = (\psi) \left(\tilde{Q}_t^K + \tilde{K}_t - \tilde{N}_t \right) \tag{3.21}$$

$$\begin{aligned} \frac{\tilde{N}_t}{\nu F} &= \left(\frac{Q^K K}{N}\right) \tilde{F} - \left(\frac{Q^K K}{N} - 1\right) (\tilde{R}_{t-1}^L - \pi_t) \\ - (\psi) \left(\frac{Q^K K}{N} - 1\right) (\tilde{Q}_{t-1}^K + \tilde{K}_{t-1}) &+ (\psi) \left(\left(\frac{Q^K K}{N} - 1\right) + 1\right) \tilde{N}_{t-1} \end{aligned} \quad (3.22)$$

$$\tilde{Y}_t = \tilde{A}_t + \alpha \tilde{K}_{t-1} + (1 - \alpha) \tilde{H}_t \quad (3.23)$$

$$-\left(\frac{1}{Q^K}\right) \tilde{Q}_t^K = x \tilde{x}_t - \chi_I (\tilde{I}_t - \tilde{I}_{t-1}) + \beta_w \chi_I (\tilde{I}_{t+1} - \tilde{I}_t) \quad (3.24)$$

$$\tilde{K}_t = (1 - \delta) \tilde{K}_{t-1} + \delta (\tilde{x}_t + \tilde{I}_t) \quad (3.25)$$

$$\tilde{R}_t = \varrho_\pi \tilde{\pi}_t + \varrho_Y \tilde{Y}_t + \varepsilon_{R_t} \quad (3.26)$$

$$\tilde{Y}_t = \frac{C^w}{Y} \tilde{C}_t^w + \frac{C^b}{Y} \tilde{C}_t^b + \frac{I}{Y} \tilde{I}_t + \frac{G}{Y} \tilde{G}_t \quad (3.27)$$

$$\tilde{C}_t = \frac{C^w}{C} \tilde{C}_t^w + \frac{C^b}{C} \tilde{C}_t^b \quad (3.28)$$

$$\tilde{A}_t = \rho_A \tilde{A}_{t-1} + \varepsilon_{A_t} \quad (3.29)$$

$$\tilde{x}_t = \rho_x \tilde{x}_{t-1} + \varepsilon_{x_t} \quad (3.30)$$

$$\tilde{e}_t = \rho_e \tilde{e}_{t-1} + \varepsilon_{e_t} \quad (3.31)$$

$$\tilde{G}_t = \rho_G \tilde{G}_{t-1} + \varepsilon_{G_t} \quad (3.32)$$

$$\tilde{\psi}_t = \rho_\psi \tilde{\psi}_{t-1} + \varepsilon_{\psi_t} \quad (3.33)$$

$$\tilde{\Gamma}_t = \rho_\Gamma \tilde{\Gamma}_{t-1} + \varepsilon_{\Gamma_t} \quad (3.34)$$

$$\tilde{\mu}_t = \rho_\mu \tilde{\mu}_{t-1} + \varepsilon_{\mu_t} \quad (3.35)$$

$$\tilde{m}_t = \rho_m \tilde{m}_{t-1} + \varepsilon_{m_t} \quad (3.36)$$

$$\tilde{r}_t^K = \tilde{m}c_t + \tilde{Y}_t - \tilde{K}_{t-1} \quad (3.37)$$

$$\tilde{W}_t = \tilde{m}c_t + \tilde{Y}_t - \tilde{H}_t \quad (3.38)$$

$$\tilde{\pi}_t = \beta_w \tilde{\pi}_{t+1} + \frac{(1 - \beta_w \phi_p)(1 - \phi_p)}{\phi_p} \tilde{m}c_t \quad (3.39)$$