

Table 1: Parameter values

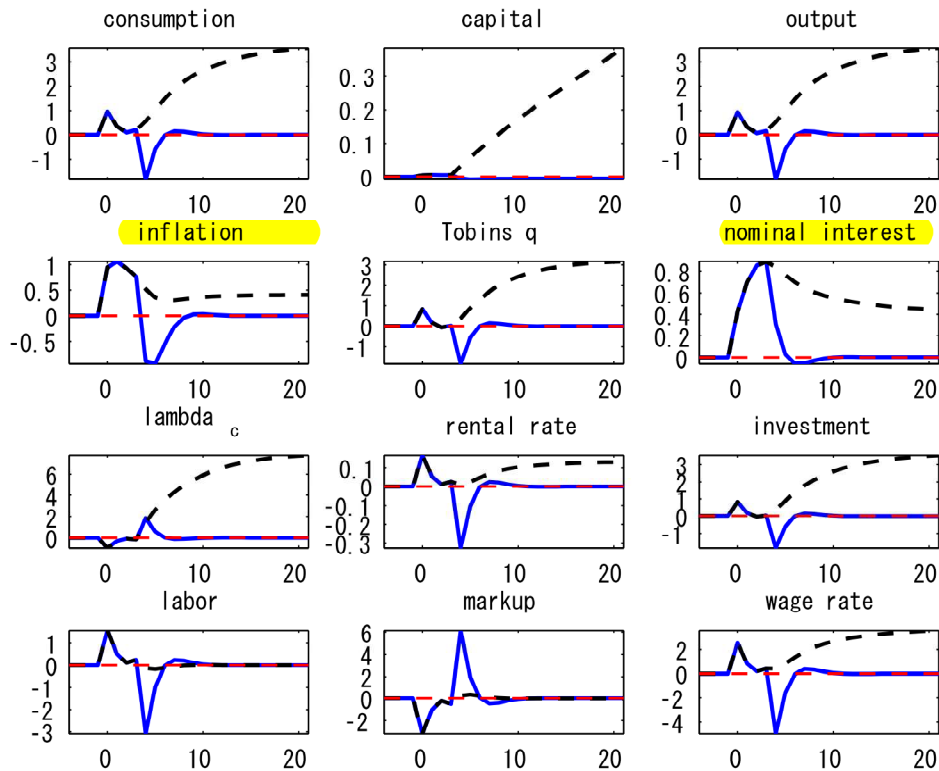
parameter	symbol	value
discount factor of households	$\beta$	1.01358 <sup>0.25</sup>
weight of disutility of labor	$\gamma$	109.82
Frisch elasticity	$\sigma_n$	1
share of capital in production	$\alpha$	0.4
price elasticity of investment to Tobin's $q$	$\sigma_\Phi$	1.01
depreciation rate of capital	$\delta$	0.025
persistence of technology growth	$\rho_g$	0.83
persistence of technology level	$\rho_A$	0.83
steady-state technology growth	$g$	0
steady-state technology level	$A$	1
probability of price change	$1 - \kappa$	0.36
price indexation	$\eta$	0.84
steady-state gross inflation	$\pi$	1
steady-state markup	$X$	1.2
persistence of nominal interest rate	$\rho_R$	0.81
weight of inflation in Taylor rule	$\rho_\pi$	1.95
weight of output in Taylor rule	$\rho_y$	0.18
lag of news shock	$p$	4

change,  $1 - \kappa$ , is 0.36 and the fraction of backward-pricing firms,  $\eta$ , is 0.84.<sup>5</sup> The steady-state gross inflation,  $\pi$ , is 1, and the steady-state markup,  $X \equiv \theta/(\theta - 1)$ , is 1.2. The persistence of nominal interest rate,  $\rho_R$ , is 0.81. The weights of inflation and output gaps,  $\rho_\pi$  and  $\rho_y$ , in the Taylor rule are 1.95 and 0.18, respectively. The persistence of exogenous technologies,  $\rho_g$  and  $\rho_A$ , is 0.83. However, NDBC's are generated even if  $\rho_g = 0$  and  $\rho_A = 0$ . The steady-state technology growth,  $g$ , is set to zero in order to see the effects of news shocks to abstract from the scaling effect, which does not change the properties of our model on NDBC's. The steady-state technology level,  $A$ , is normalized to one. The price elasticity of investment  $\sigma_\Phi$ , is 1.01.<sup>6</sup> The values of  $\bar{a}$  and  $\bar{b}$  are determined as a solution of  $\Phi(0) = 0$  and

<sup>5</sup>A standard calibrated value of  $1 - \kappa$  is 0.25 in the literature. The sticky price is the key to generate NDBC's in our model, but the degree of the stickiness is not important. Our model can generate NDBC's if  $1 - \kappa = 0.25$ .

<sup>6</sup>To guarantee a positive value of  $\bar{a}$ , the value of  $\sigma_\Phi$  should be greater than one. This is shown by the steady-state equilibrium conditions. Our result is robust to the value of  $\sigma_\Phi$ . If  $\sigma_\Phi$  is very close to one or if  $\sigma_\Phi$  is large, like 1.5, NDBC's are generated.

Figure 1: NDBC to growth news shock

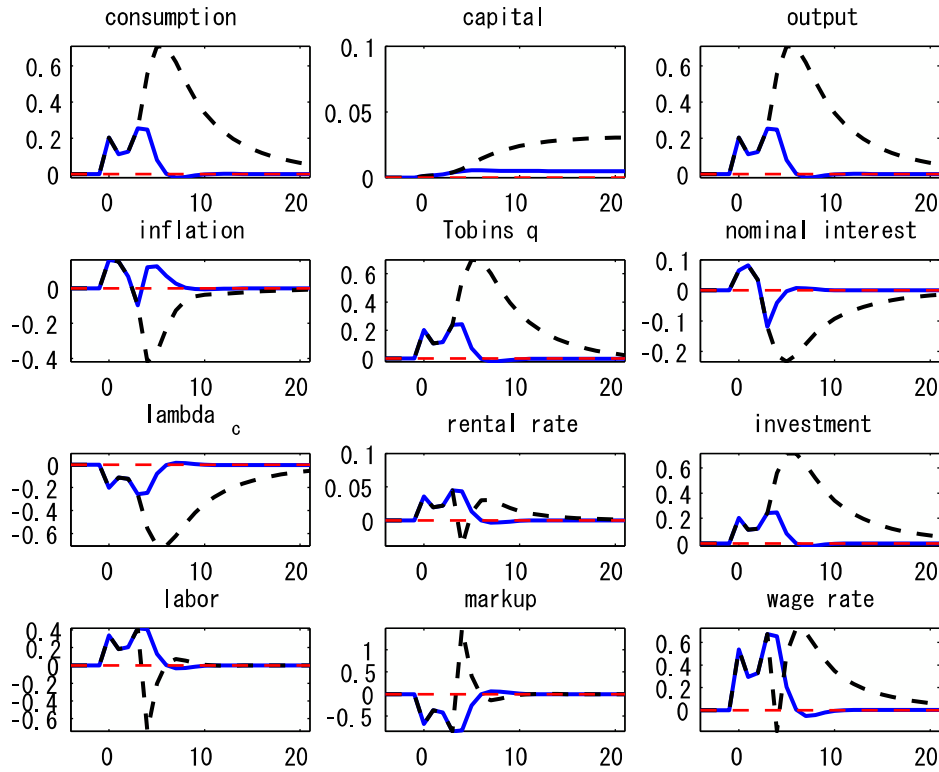


Notes: The dashed lines show cases where the news occurs at  $t = 0$  and it materializes at  $t = 4$ . The solid lines show cases where the news occurs at  $t = 0$  and turns out to be false at  $t = 4$ . The vertical axes are percentage deviations from the steady-state values (inflation, nominal interest rate, markup and rental rate are level deviations), and the horizontal ones are quarters.

and the decrease of markups. The decrease of markups increases inflation through the New Keynesian Phillips Curve. This is the mechanism why technology growth shock increase inflation. In the case of news shock, which implies future technology growth shock, inflation is expected to occur in the future by this mechanism.

The New Keynesian Phillips Curve (8) implies that future inflation results in the current inflation. While the current optimal price level also increases, price-setting firms cannot fully increase their prices because of nominal rigidities and it leads to the decrease of their markups. The decrease of markups induces the increase of aggregate demand and output and labor input increase. Finally, household income

Figure 3: NDBC to level news shock



Notes: The dashed lines show cases where the news occurs at  $t = 0$  and it materializes at  $t = 4$ . The solid lines show cases where the news occurs at  $t = 0$  and turns out to be false at  $t = 4$ . The vertical axes are percentage deviations from the steady-state values (inflation, nominal interest rate, markup and rental rate are level deviations), and the horizontal ones are quarters.

This mechanism is easily verified by the intratemporal optimization condition:

$$\gamma c_t n_t^{\sigma_n} = \frac{1 - \alpha}{X_t} \left[ \frac{k_{t-1}}{n_t} \right]^\alpha A_t \zeta_t^{1-\alpha}. \quad (18)$$

In standard RBC models, an increase of consumption  $c_t$  from news about the future implies decreases of labor input  $n_t$  since markup  $X_t$  is constant over time and current capital stock  $k_{t-1}$  and current technologies  $A_t$  and  $\zeta_t$  do not change. Thus, output and investment also decrease. However, in our model, comovements are made possible by the decrease of markup.

$$\hat{R}_t = \rho_R \hat{R}_{t-1} + (1 - \rho_R) \left[ \rho_\pi E_t \hat{\pi}_{t+1} + \rho_y \hat{y}_t \right] + \varepsilon_t^R + v_{t-p}^R,$$

given the evolution of technologies. Note that we ignore the costs of price dispersion since it is approximated to one in the neighborhood of the steady state. For detrending, we introduce the detrended variables

$$\tilde{G}_t \equiv \frac{G_t}{\zeta_t},$$

for  $G = c, k, i, y, w$ , and

$$\tilde{\lambda}_{c,t} \equiv \frac{\lambda_{c,t}}{\zeta_t^{-1}}.$$

The detrended equilibrium system is as follows.

$$\frac{1}{\tilde{c}_t} = \tilde{\lambda}_{c,t},$$

$$\gamma \tilde{c}_t n_t^{\sigma_n} = \tilde{w}_t,$$

$$q_t = \beta E_t \left[ \frac{\tilde{\lambda}_{c,t+1}}{\tilde{\lambda}_{c,t}} (1 + g_{t+1})^{-1} \left\{ (1 - \delta) q_{t+1} + r_{t+1} + q_{t+1} \left[ \Phi \left( \frac{\tilde{i}_{t+1}}{\tilde{k}_t} (1 + g_{t+1}) \right) - \Phi' \left( \frac{\tilde{i}_{t+1}}{\tilde{k}_t} (1 + g_{t+1}) \right) \frac{\tilde{i}_{t+1}}{\tilde{k}_t} (1 + g_{t+1}) \right] \right\} \right],$$

$$1 = \beta E_t \left[ \frac{1}{\pi_{t+1}} \cdot \frac{\tilde{\lambda}_{c,t+1}}{\tilde{\lambda}_{c,t}} (1 + g_{t+1})^{-1} R_{t+1} \right],$$

$$\tilde{y}_t = A_t \left[ \frac{\tilde{k}_{t-1}}{1 + g_t} \right]^\alpha n_t^{1-\alpha},$$

$$\tilde{w}_t = \frac{1 - \alpha}{X_t} \cdot \frac{\tilde{y}_t}{n_t},$$

$$r_t = \frac{\alpha}{X_t} \cdot \frac{\tilde{y}_t}{\tilde{k}_{t-1}} (1 + g_t),$$

$$q_t = \left[ \Phi' \left( \frac{\tilde{i}_t}{\tilde{k}_{t-1}} (1 + g_t) \right) \right]^{-1},$$

$$\tilde{k}_t = \frac{1 - \delta}{1 + g_t} \tilde{k}_{t-1} + \Phi \left( \frac{\tilde{i}_t}{\tilde{k}_{t-1}} (1 + g_t) \right) \frac{\tilde{k}_{t-1}}{1 + g_t},$$

$$\hat{\pi}_t = \frac{\beta}{1 + \eta \beta} E_t \left[ \hat{\pi}_{t+1} \right] + \frac{\eta}{1 + \eta \beta} \hat{\pi}_{t-1} - \frac{(1 - \kappa)(1 - \kappa \beta)}{\kappa(1 + \eta \beta)} \hat{x}_t,$$

$$\tilde{c}_t + \tilde{i}_t = \tilde{y}_t,$$

$$\hat{R}_t = \rho_R \hat{R}_{t-1} + (1 - \rho_R) \left[ \rho_\pi E_t \hat{\pi}_{t+1} + \rho_y \hat{y}_t \right] + \varepsilon_t^R + v_{t-p}^R,$$